# RS-140 Side-mounted Flat Door Opener

Chapter 1: Product introduction	2
1.1 Workflow	2
1.2 Product Characteristics	3
1.3 Main Technical Parameters	3
Chapter 2 : Installation	4
2.1 Installation of mechanical part of door opener	
2.2 Connection of electrical part of door opener	
Chapter 3: Parameter Setting and State Display	11
3.1 Parameter Setting	11
3.2 State Display Description	14
3.3 Error Alarm	14
Chapter 4: Debugging	14
4.1 Closing Position Learning	
4.2 Opening Debugging	
4.3 Closing Debugging	
1.4 Other Debugging	
Chapter 5: Common Troubles and Removal	16
Parking List	

## Chapter 1 Product Introduction

In order to meet the automation requirements of modern flat-opening door, our company has developed and produced intelligent automatic door opening/closing machine, which adopts microcomputer chip, digital control, powerful function, high safety performance, easy installation and debugging.

Note: In order to use the equipment better and more comprehensively,

please read the operation instructions carefully before you install and use it.

#### 1.1Workflow:

#### A. Main Process:

open the door-----close the door-----close & slow down-----keep in place-----close the

#### B. Detailed Workflow:

**Step 1:** The open signal from external equipment triggers the electromagnetic lock of the door-opener to shut down.

**Step 2:** Open the door (permissible speed 1 to 10 gears, see Chapter3).

**Step 3**: Open & slow down(permissible speed 1 to 9 gears, see Chapter 3).

Step 4: Stop it.

**Step 5:** Open &hold (permissible time 1 to 99 seconds, see Chapter 3).

**Step6:** Close the door (permissible speed 1 to 9 gears, see Chapter 3).

**Step7:** Close & slow down(permissible speed 1 to 9 gears, see Chapter 3)

Step8: Electromagnetic lock power on.

**Step9:** Presse door closed.

End of a workflow.

Note: In the process of closing the door, if there is a trigger signal for opening the door, the action of opening the door will be executed immediately.

#### 1.2 Product Characteristics

- 1). Low consumption, static power :0.5W, maximum power: 25W.
- 2). Super silence, working noise less than 50 d B.
- 3). Small size, easy installation.
- 4). Powerful, maximum push door weight 140 Kg.
- 5). Support multiple signal input, relay signal, voltage signal (5-24V).
- 6). motor over-current, overload, short-circuit protection.
- 7). Intelligent resistance, push-door reverse protection.
- 8). Motor current (thrust), speed accurate regulation.
- 9). Self-learning limitation, abandoning tedious limitation debugging.
- 10). Enclosed shell ,rain and dust proof.

#### 1.3 Main Technical Parameters

Product Types	Type 140		
Range of application	Various flat-open doors with the width ≤ 1200mm and the		
	weight ≤ 120Kg		

Open Angle	90°
Power Supply	DC24V 5A
Rated Power	25W
Static Power	0.5W ( no electromagnetic lock )
Open/Close Speed	1-9 gears, adjustable (corresponding opening time 10-3S)
Open Hold Time	1~99 seconds
Operating	-20°C ~ 60°C
Temperature	
Operating Humidity	30% ~ 95%(no condensation)
Atmospheric Pressure	700hPa ~ 1060hPa
External Size	Long 360mm*Wide 83mm*High 131mm
Net Weight	about 7.3kg
Three-Guarantee	One year
Period	

## **Chapter 2 Installation**

#### **Installation Notes**:

A. Considering the influence of wind resistance, force arm and other factors, the maximum width of the door for the door opener is 1.6 meters. The weight of the

door should be less than 90 kg, the width of the door should be reduced by 0.1 meters, and the weight can be increased by 10 Kg. By analogy, the width of the door with 1.1 meters can reach 140 Kg, slightly overweight will not affect the life of the door opener. But it will affect the opening/closing speed.

B. Installation must be carried out according to the size provided in the instructions.

Improper Installation will directly cause the door opener to fail to work properly and damage the equipment in serious cases.

C. During installation, it is forbidden to change the structure of the door opener. and no holes can be made in the shell to avoid water and air entering and causing electronic and electrical components failure.

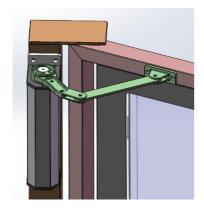
### 2.1 Installation of mechanical part of door opener.

#### 2.1.1 Installation instructions:

A. Distinction of left/right door opening: Clockwise door opening direction is left door, conversely, counter-clockwise door opening direction is right door.

B. The door opener should be mounted vertically with the door post. Pay attention to the rotation direction of the connecting rod. Installation is as follows:

#### **Left Open Door:**





#### **Right Open Door:**



C. Install the main body of the door opener according to the size provided in 2.1.2 and 2.1.3.

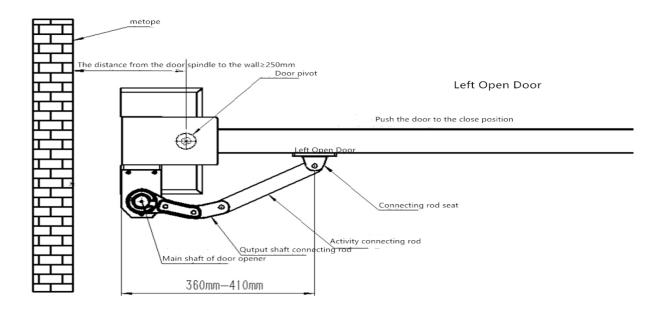
D. Remove the crank fixed screw and gasket from the main shaft of the door opener.

E. Put the perforated end of the crank assembly into the main shaft of the door opener. Remember to make the position of the keyway on the hole aligned with the key of the main shaft, next lock the crank with gasket and screw.

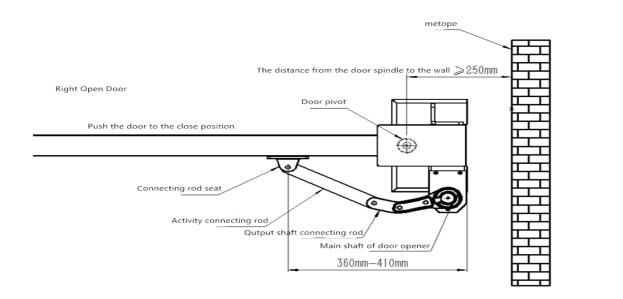
F. Fix the L-type mounting seat on the crank to the door ,with the fixed screw M8\*70 and the flat cushion nut M8.

Note: When installing, the L-type mounting seat, crank and main shaft of the door opener should be on the same horizontal plane. Otherwise, the crank up and

down plane will be forced and blocked.



## 2.1.3 Right open door installation method and size.



#### 2.2 Connection of electrical part of door opener

#### 2.2.1 Description of the control port:

Warning: A. When the electrical part is connected, live work is strictly prohibited. Power can be energized after all connections. B. Do not connect the positive and negative poles of the power supply inverse, otherwise the equipment will be damaged. Note: A. Pleas choose an electromagnetic lock whith supply voltage is 12V DC and the power ≤9W or our company's electromagnetic lock. Otherwise it will cause abnormal operation or circuit damage. B: When leaving factory, the motor wire has been connected, do not take it out without any special case. C: Opening signal of external access control equipment: a: When the access control equipment is the output of switch quantity (dry contact), the close switch controls the opening of the door, and the switch should be open usually, without polarity requirements. b: When voltage output (wet contact), add transfer module.

Name	Open		Fire		Electromagn-et		Power Supply		
	Doc	r Co	ntrol	ol fighting		ic lock			
		Signal		linkage					
door opener	+12	N	GND	FIR	GND	+12V	Neg-a	GND	+24V
	V	o					tive		
Switchi-ng Power								сом	+V
								or-V	
Electro-m agneti-c						Red	black		
Lock						line	line		
Access Control	+12	N	сом						
Machine	V	o	GND						

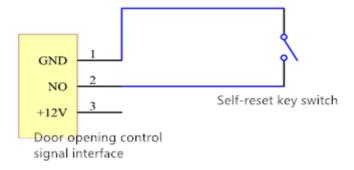


	GND
	Infrared photoelectric switch
	interface (Note: please use NPN
Infrared photoelectric switch	normal open type)
interface (Note: please use NPN	Infrared photoelectric switch
normal open type)	interface (Note: please use NPN
	normal open type)
	+12VDC

### 2.2.2 Diagram of control signal wiring

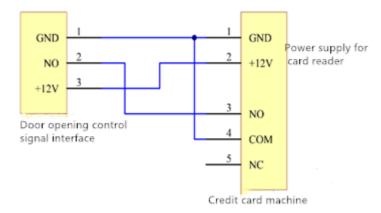
Connect power supply, electromagnetic lock and external door opening control equipment according to the diagram. After checking , start the power commissioning.

## 1. Exit button switch connects the control signal of door opener:

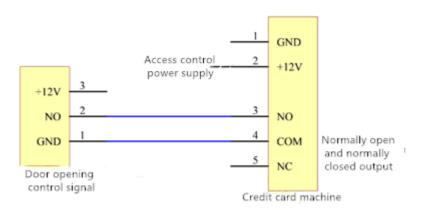


## 2.Access Control machine Connects the control signal of door opener:

#### the first connection:



#### the second connection:

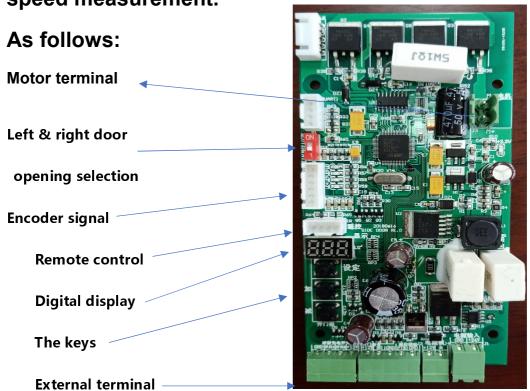


Note: All door opening signals should connect to the same point (GNG, NO)

## **Chapter 3** Parameter Setting and State Display

## 3.1 Circuit Board Diagram

The CNC board for door opener uses 3-bit LED digital tube to display and three keys to set parameters. The dial switch is used to select the right and left switches. Jumper selection door opening control signal input is relay or voltage mode. Check each indicator indicating the power supply normally and the Hall state of speed measurement.



3.2. After installation and wiring , turn on the power and the door opener will enter the learning state of the closing position (digital tube display "H07" ) .

After close and finish learning , it enters the standby state, and the digital tube displays"\_ \_ \_ "in the standby state.

## 3.3. Function and corresponding digital tube display

Dis-pl	Explain	The default	Range8	Remarks
ay		value		
P <b>01</b>	Closing speed	6	1–10	The numerical value
				larger, the speed
				faster.
P <b>02</b>	Closing slow speed	3	1–10	The numerical value
				larger, the speed
				faster.
P <b>03</b>	Closing delay	5	1-15	Force the door close in
				place.
P <b>04</b>	Opening &holding time	5	1-99	Residence time after
				opening the door in
				place.
P <b>05</b>	Closing slow angle	30	5-60	The numberical value
				larger, the angle
				larger.
P <b>06</b>	Current Detection (High Speed)	110	20-240	Unit is 0.01A
P07	Wind resistance time	3	1-10	Unit is S
P08	Left & Right open door	3	=1 left open door	Default 3: Open the door
			=2rightdoor =3	according to the red
			testing	dial switch on the
				circuit board.
P <b>09</b>	Auto-induction open and	1	=1 induction =2	at1 When the door is not
	close position		non-induction	closed in position , it
				will close again
P10	Open speed	7	1-10	The numerical value
				larger, the speed
				faster.
P11	Opening slow speed	3	1–10	The numerical value

				larger, the speed
				faster.
D10	0	15	5 60	
P12	Opening slow angle	15	5-60	The numerical value
				larger, the angle
				larger.
P13	Open angle	135	50-200	Open angle
P14	Factory holds	5	1-10	Factory holds
P15	Factory reset	2		66Factory rest
				01Working mode sounds
				02Working mode silent
				05 Display the number of
				people in and out
				88 Clear the number of
				people in and out
				03 Test program
P16	Factory holds	5	1–20	Factory holds
P17	Factory holds	15	1–60	Factory holds
P18	Delay before opening	2	1-60	1 means 0.1S
P <b>19</b>	Low-speed current	35	20-150	Unit 0.01A
P22	Remote mode selection	1	1-2	1. Inching (all keys
				can be used as open
				key, the door
				opening time
				delay to automatic
				closing)
				2. Interlocking (press
				open key to open the
				door and keep it open
				normally, need to press
				close key to close).
P23	Factory holds	10	1-10	Factory holds
P24	Selection of Magnetic	1	1-2	1Magnetic lock(power on
	/Electronic Lock			and lock) 2
				Electronic control lock
				((power on and open)
P25	Factory holds			Factory holds
P26	Coefficient of downwind	4	1-10	0 Maximum wind
	resistance			resistance
L		L	L	

### 3.2. State Display Description

### Work Display H01 - H09

Dis-play	Explain	Remarks
	Hold State	Standby without work
H01	High speed open door	Open the door high speed
H02	Open &slow	Open stop &slow down
Н03	Open& slow Delay	Open stop& slow down
H04	Open& hold	Open in place& hold
H05	High speed close door	Close the door high speed
H06	Close& slow down	Close stop& slow down
H07	Close door in place Delay	Close door in place
H08	Push-door Protection	If the motor driving current is too high
		when open/close door, or push the door
		reverse.
H09	Fast Protection	
	for back-push door	

#### 3.3.Error Alarm

#### Work Display E01 - E04

Display	Explain	Remarks
E01	Report error of open door	
E02	Report error of close door	
E03	Close stop error	
E04	Hall detection error	

## **Chapter 4 Debugging**

#### 4.1 Closing Position Learning

A. Normal state: Power on, the digital tube on the circuit board shows "H07", and the door moves slowly towards closing automatically(in the learning

closing position), waiting for the door to close in place and digital display "---";

B. Abnormal state: Power-on, the door repeatedly switchs back and forth, then set the P15 parameter as 02, when power on again, and then observe whether it enters the normal state A.

C. Abnormal state: Power-on, the digital tube on the circuit board shows "H07".

When the door moves towards opening ,please refer to(3.1) and dial the open direction dial switch(red) on the circuit board to the opposite direction, and then observe whether it enters the normal state A.

Note: please do not block when learning closing position, otherwise the blocking position will be regarded as the closing position!

#### 4.2 Opening Debugging

A. Opening Angle: if the opening Angle is not enough, increase the value of P13; if it is too large, decrease the value of P13 to reach the desired Angle.

B. Opening speed: adjust the value of P10, the larger the value, the faster the speed, the smaller the slower speed.

C. Time of open and hold: When the door open in place, the time of stopping at the position, and adjust the value of P04 (in seconds).

#### 4.3. Closing Debugging

A. Closing speed: Adjust the value of P01, the larger the value, the faster the speed, the smaller the slower;

B: Close-slow Angle: Adjust the value of P05, the larger the value, the larger the Angle, the smaller value the smaller angle.

#### 4.4.Other Debugging

#### A: Adjust backpushing current:

Set P06, factory value is 110, that is, set motor working current to 1.10A.If the motor works abnormally and the LED digital tube shows "H08" alarm, the P06 value must be increased.

- B. If the door is not closed in place, increase the value of P19 or P02.
- C. If the close buffer speed is too fast, the PO2 value can be reduced.
- D. Please refer to 3.1 for setting other parameters, it should be according to the situation on site.

## **Chapter 5: Common Troubles and Removal**

Fault phenomena	Fault Jı	Treatment	
			Measures
No working, and	Use a multimeter	24V	1. Check & replace
the 3.3v power	to Check whether		24V power supply.
indicator and	there is a 24V		2. Check & replace
digital tube do	voltage at the		wiring.
not light.	two points of	no 24V	Replace the
	"power input" on		circuit board.
	the circuit board		
	terminals.		
No working,	Set P6 parameters	Problem solve	End
digital tube	by referring to		

display"H08"	3.1.3, increase	Fault remain	1. Replace the
	high-speed		motor.
	current		2. Replace the
	(high-speed		circuit board.
	torque), and		3. Disconnect the
	restart the work.		connection from
			the door to the
			rocker arm and
			check whether the
			door is blocked.
Open not in place	Increase the value	e of P13 ,increase	the angle of open
	door .		
0pen	Increase the value	of P 12, increase t	t <b>he buffer angl</b> e of
without buffer	open door.		
Close not in place	Increase the value	e of P19 , increa	se the value of
	low-speed current	(low-speed torque	e), or increase the
	value of P2 , in	crease the buffer	speed.
Close	Increase the value	e of PO5, increase	t <b>he buffer angle</b> of
without buffer	close door.		
When the door is	Use a multimeter	12V	1. Check and
closed, the lock	to Check whether		adjust the
cannot lock the	there is a 12V		electromagnetic
door.	voltage at the		lock , make it
	two points of		flat with the
	"electromagnetic		iron plate.
	lock" on the		2. Replace the
	circuit board		electromagnetic
	terminals.		lock. 3.
			Check and replace
			the connection.
		no 12V	Replace the
			circuit board.
	I .	1	

## **Parking List**

No.	Part Name	Unit	QTY	Remarks
1	140 model	set	1	
	side-mounted door			
	opener			
2	Crank component	set	1	1 straight handle, 1
				crank, 1 L-type
				mounting seat.
3	Installation screw	bag	1	2 round pins M10*25, 6
				Flat pads M10, 2 open
				pins, 2 screws M8*70,
				6 nuts M8; 4 screws
				M8*110.
4	Switching Power	Piec-e	1	AC220
	DC24V 5A			